

# Amish Jariwala

4<sup>th</sup> Year Mechanical Engineer at



## Key Values (ENFJ-T)

Applying engineering fundamentals and continuous learning to deliver high-impact solutions.

# Career Development

- Expected BSME Graduation Dec. 2026
  - In +1 Year Masters Program (MSME) - Dec 2027
- Manufacturing Engineering, 9 Months
  - 3 months @ P&G
  - 6 months @ Rivian
- Academic Research, 2+ Years
  - First-author, peer-reviewed paper validating video-based crane tip-over analysis submitting to ACC under ASME for 2025

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1. BIW Hood	Engineering (Rivian)
2. Early Concept Car DFM	Design for Manufacturing (Rivian)
3. Advanced Crane Lab	Research
4. Competition Robot	Robotics / Mechatronics
5. Pallet Defect Detection	Automation/Quality Control (P&G)
6. SAP Automation (PM+)	Automation (P&G)
7. Laser Cutter Ventilation & Vinyls	Makerspace / Safety

# 1. Rivian R2 Hood

## Full Line Ownership for the Rivian R2 Hood

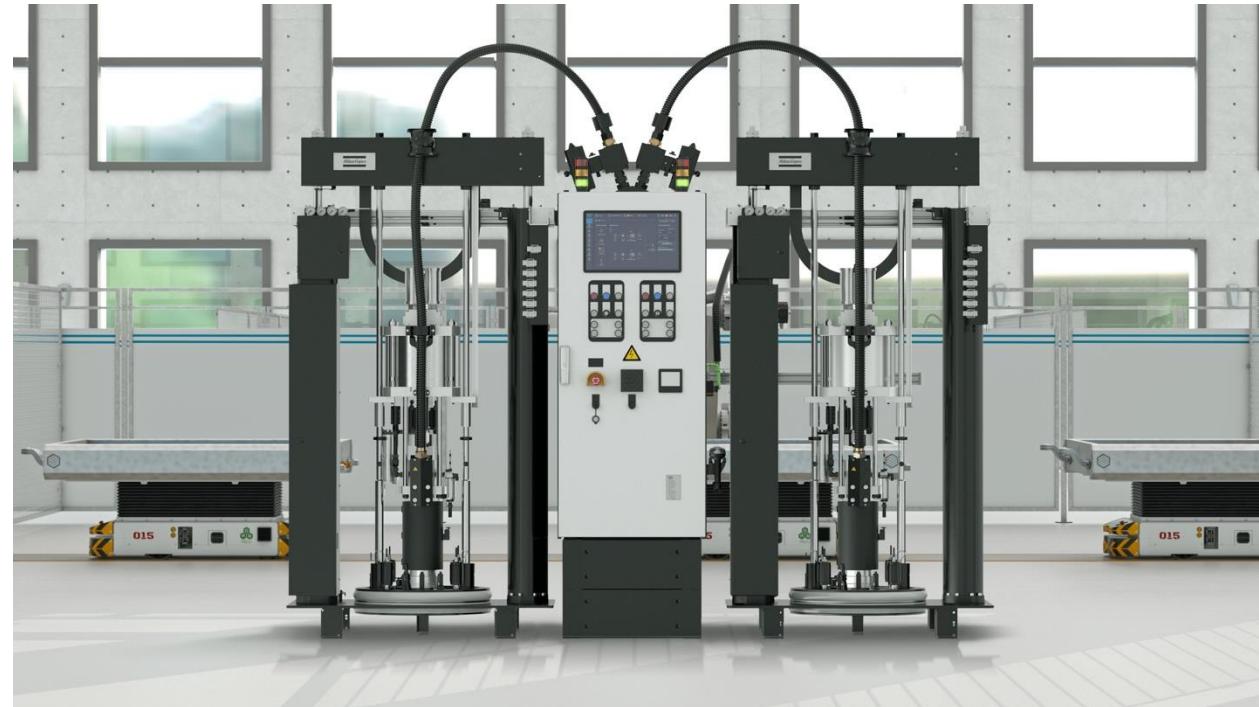
- Design – **CATIA V6**
  - Calculated the optimal flange and transition length for corner hemming in aluminum closures using **Assembly Autoform**
  - Authored 9+ change approvals to remove tooling and fixture clashes
  - Rapid prototyped jigs to be used in production for fit & finish
- Installation
  - Mechanical, Electrical, Safety, Robotics, PLC Installation / Commissioning
  - Joining (Adhesive, Welding) Validation
    - Adhesive bead width and length within 5% tolerance
  - Dimensional (Metal Fit, Repeatability) Validation



# 1. Rivian R2 Hood

## Hood deformation + paint boil-out

- Introduced a two-part epoxy **reducing deformation in the hood by 61%** and eliminated paint boil-out defects (\$600k system)
- Contingencies
  - Implements automated roller hem cleaners
    - \$100k system implemented for production
  - Simulation
  - Cycle-Time Charts
  - Semi-Auto application while waiting on vendor manufacturing
- Completed
  1. Problem
  2. Baseline Data
  3. Solutions
  4. Risks
  5. Contingencies
  6. Vendor Buyoff



## 2. Rivian R3 / Pre-Production Design for Manufacturing

### Bill of Process / Workcell Layout for R3 Liftgate and Hood

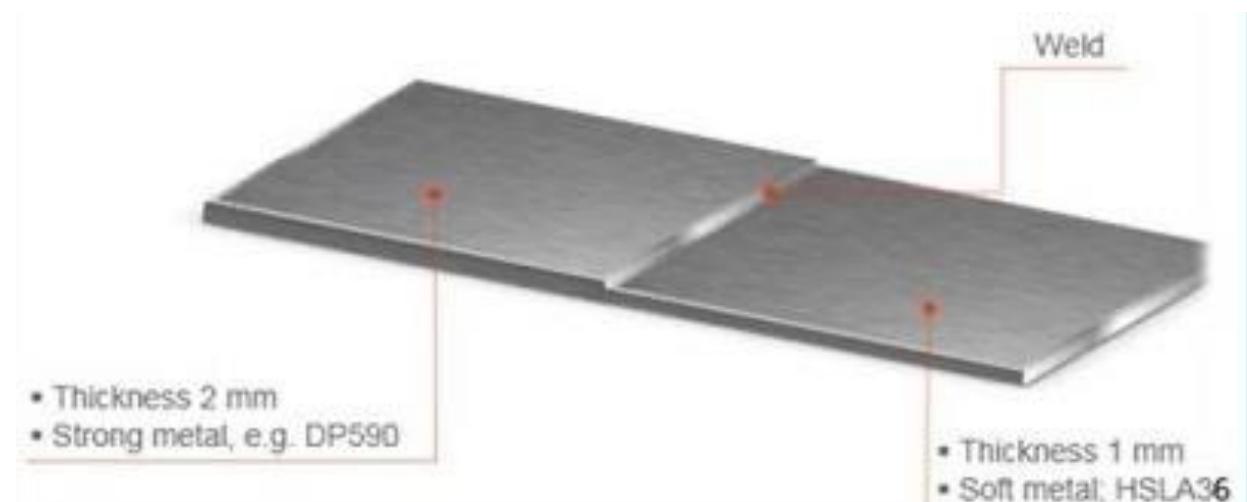
- Identified Process changes to **eliminate 4 stations** and reduce Capital Cost (CapEx) + Operational Cost (OpEx)

### Introduced Tailor/Laser Welded Blanks

- Tailor one large sheet by laser seaming in stamping to fit 2 doors instead of 1
- Reduces Bracket/Part Count by 33%, eliminating CapEx (Equipment) and OpEx (Welds)
- Savings = \$640K Capex + \$880k / year OpEx**

### Weld Time Standardization

- Added equipment and joining (Resistance Spot Welding, SPR...etc) times to standard cycle time document through 14000 weld data analysis.



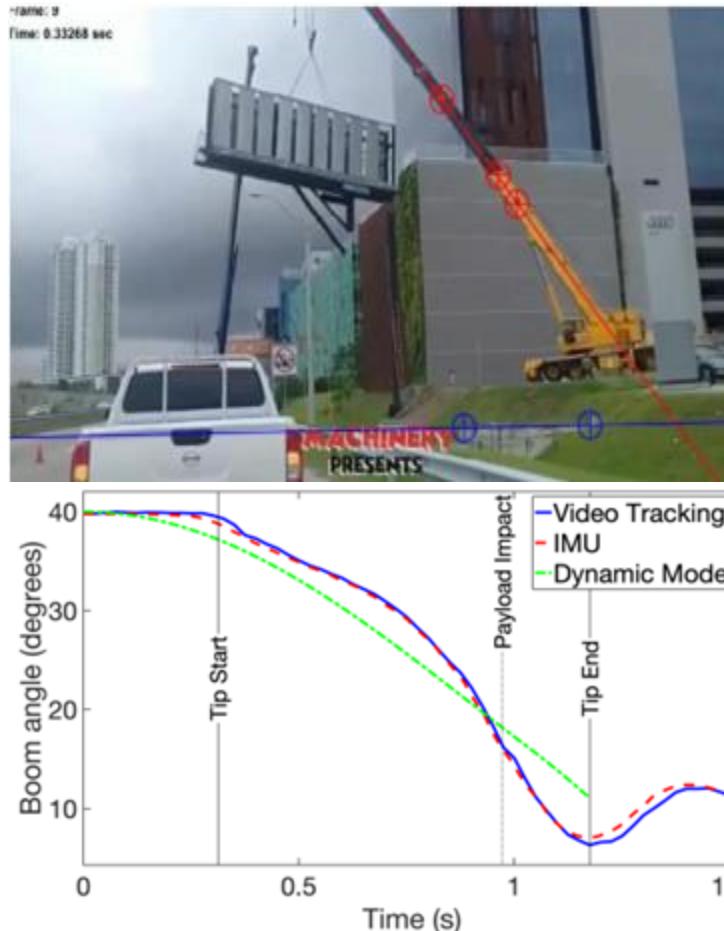
### 3. Advanced Crane Lab

#### Validated video analysis for extracting dynamic data from crane tip-overs

- Designed a 1:50 scale, tele-operated, 3d-printed model of a mobile boom crane to withstand repeated, controlled tip-over tests
- Included dynamic and kinematic calculations for inertia changes
- Yielded Incredibly strong correlation (**mean  $R^2$  value of 0.970 and a mean RMS error of 3.29°**)
- Data will be used to calibrate a MATLAB dynamic model to replicate and predict tip-over behavior
- **First author paper submitted to American Controls Conference 2026**

#### Command Shaping Implementation & Validation

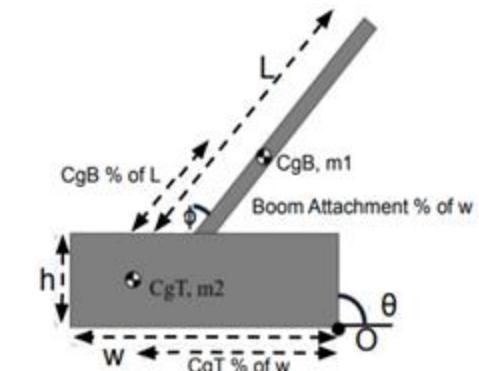
- Input shaping techniques (Zero Vibration & Extra-Insensitive) that actively suppress payload swing dynamics reducing likelihood of tip-over



Stop Crane Tip-over Fatalities

Develop Anti-Tip-over Technology

Need Verified Tip-over Data



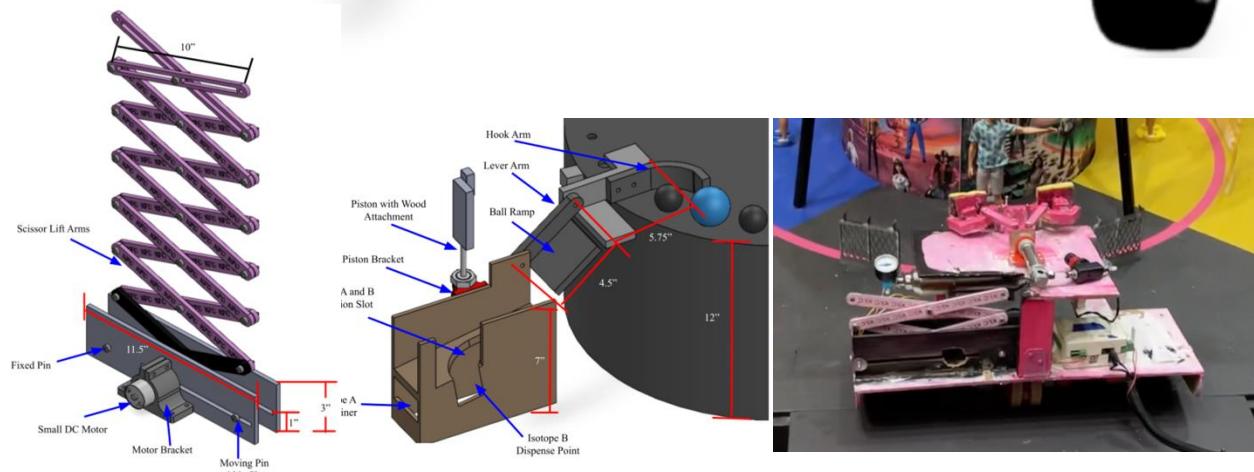
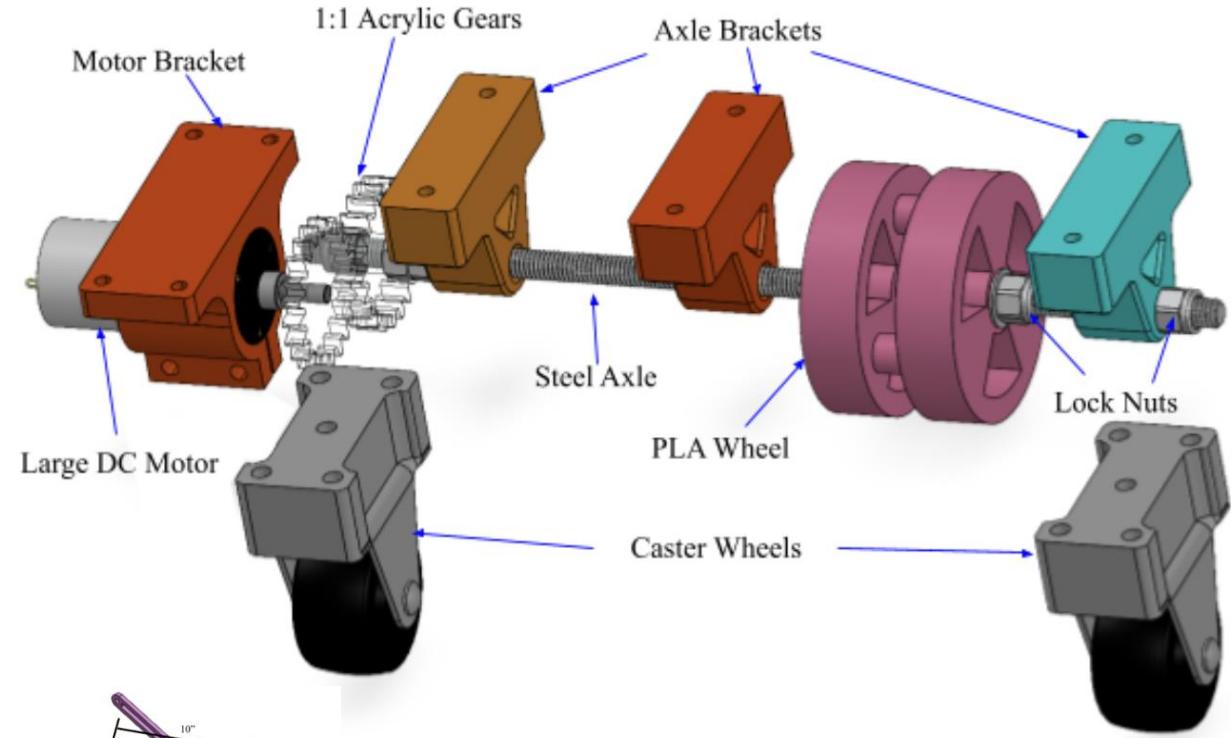
# 4. Competition Robot

Engineered a Robot to compete in the ME2110 Georgia Tech Competition, placing 4<sup>th</sup> out of 68.

- Performance standard deviation of 9%
- Delta-trike drivetrain with a single-rear wheel drive geometry
  - High-strength steel rod axle + acrylic gears adhering to cost and material calculations
- Scissor Lift with pulley system to increase tension output, overcoming 47 oz-in torque requirement with underrated 36 rated motor
- Ball Collection subsystem with internal ramp
- Pneumatic Grabber subsystem maximizing reliability despite arena tolerance variations

## Performed Failure Modes and Effects Analysis

- Identified risk priorities which informed failures and component modularity
- Quality Function Deployment, Function Trees, and Morphological Charts



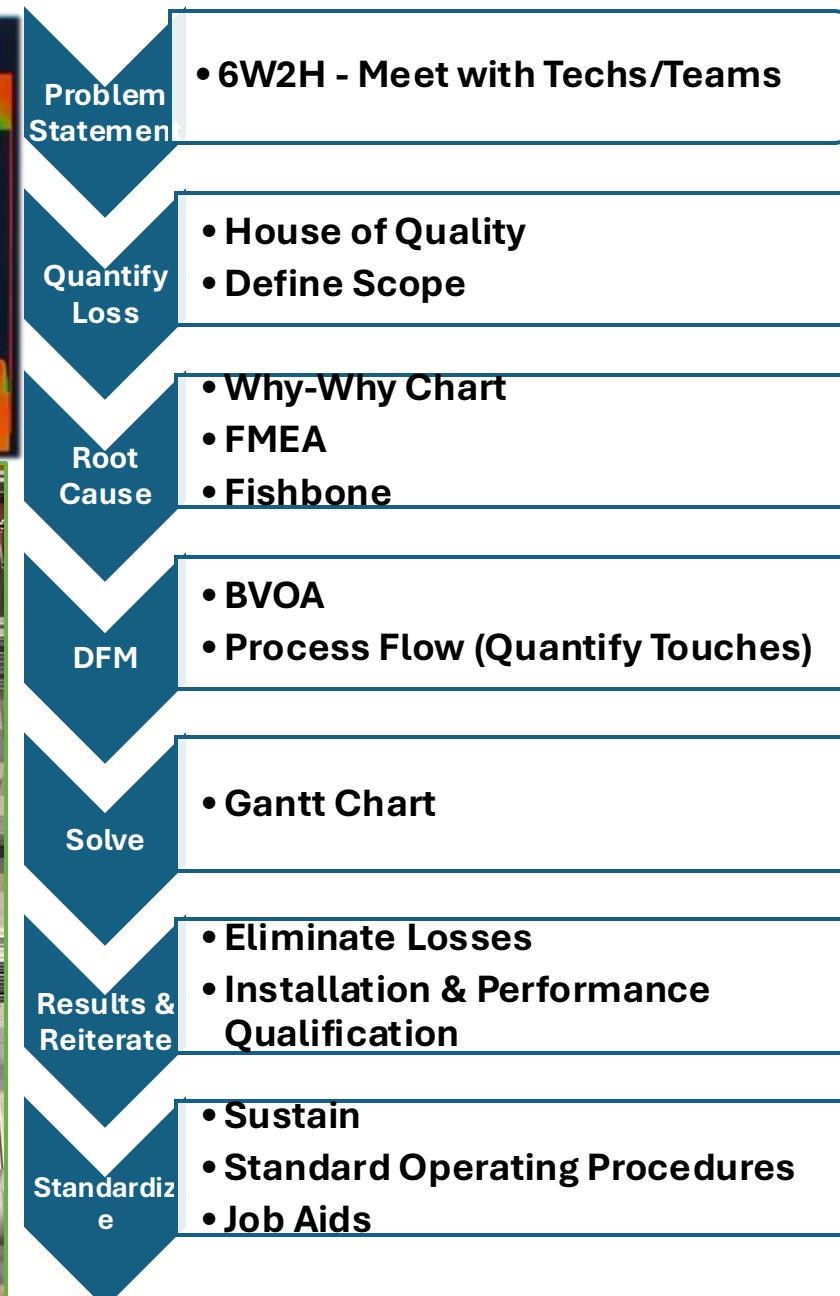
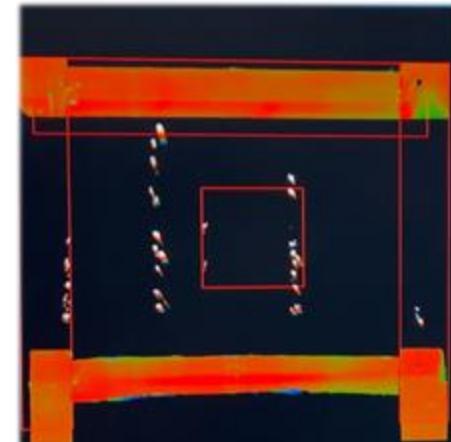
# 5. Pallet Defect Detection

## Implemented Automated System to Identify Poor Pallets and reject them

- SICK Vision System
- Created Electrical Enclosure according to NEPA & NEC
- **Eliminated 2.2K Hours annually on Interventions & Stops + safety hazards, 1.5 Headcount, & 13,000 Touches annually**
- \$200k Capital Investment - ROI 8 Years
- Immediate Safety, QA, and Touch improvements

## Implemented auto-blower

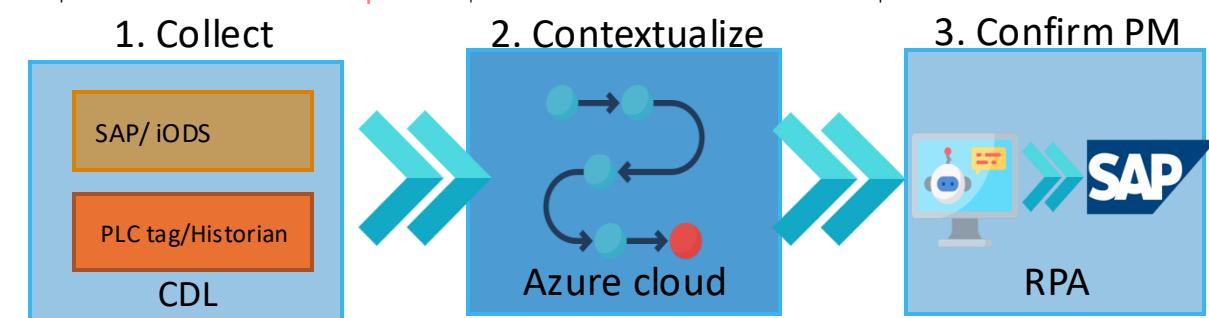
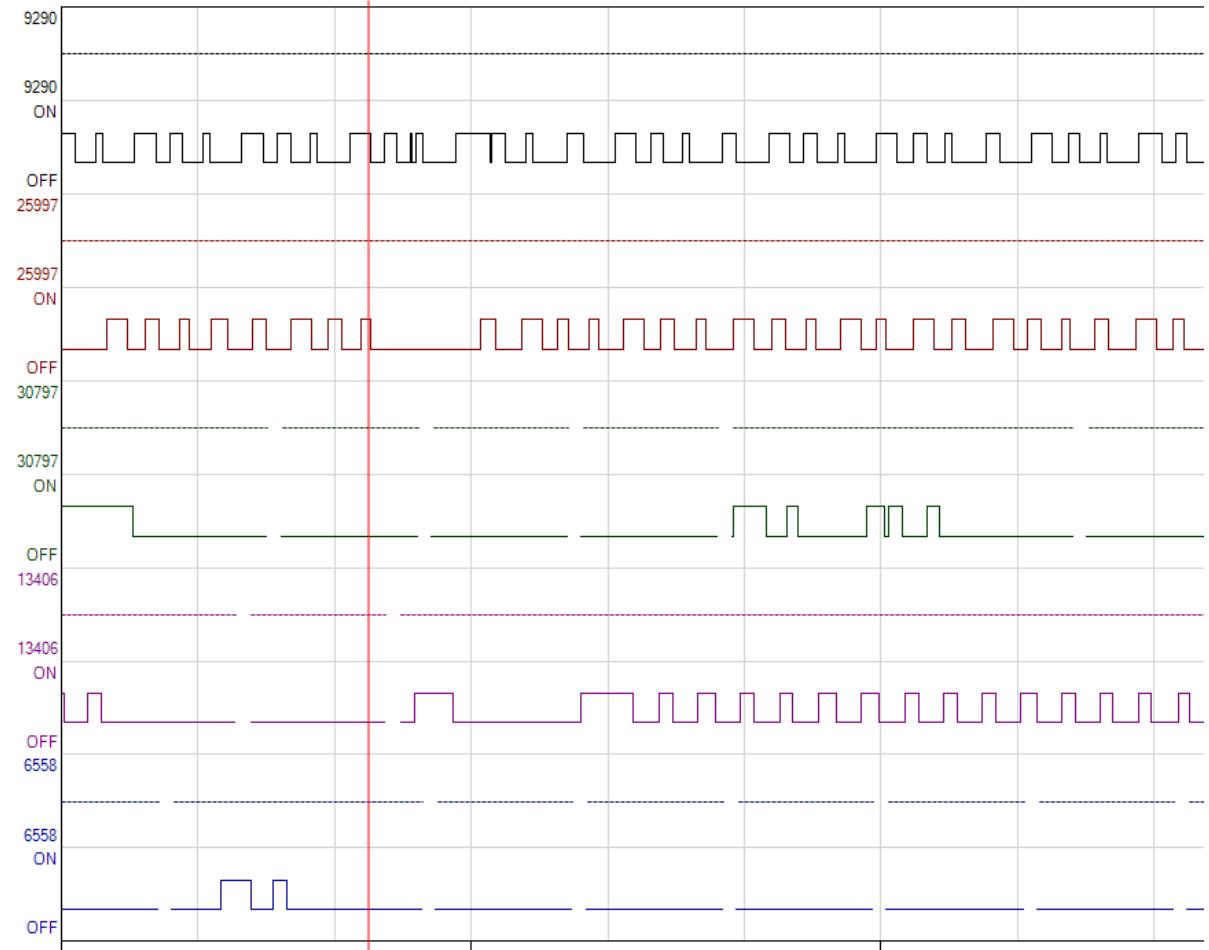
- 87.5% Reduction in False Rejects



# 6. SAP Automation

## Automated Preventative Maintenance (PM+) Orders

- Used Aveva Historian to detect once over 5000 motors cross maintenance threshold to automatically push maintenance order in SAP.
- One central solution (cloud) using standard infrastructure and data sources
- Maintenance based on feedback loop from operations (SAP/ PLC tags)
- Program is designed to support in future transition to solutions
- Ongoing cost: \$80K/year for all sites
- **Saving potential: \$5M + across sites**
- **Saved 0.6 Headcount**



# 7. Makerspace – Invention Studio

## **Volunteer Prototyping Instructor & Laser Maser**

- Entirely student-run makerspace (largest in the U.S.) serving 15k+ unique projects per semester
- Directed the operation and maintenance protocols for key rapid prototyping technologies
- Used 20k annual budget to improve and advance laser cutters in unique ways (700 hours of logged user use yearly)
- Served as technical expert, instructing in advanced techniques for lasers and embroidery machines

## **Safety Improvements**

- **Installed Fume Extractor** with multi-stage carbon filters to improve longevity and improve safety of the laser cutters

